## Service Note No. 12 - Initiation

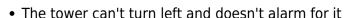
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## Description

https://wiki.envirologic.se/doku.php/cc:initiate

If last under this 2023 69101, 98:197 iation must be carried out. This is needed if:



- Current overload alarm shows when parking the boom downwards
- Actuator has been changed

## Instruction

- 1. Park robot in manual mode
- 2. In the recipe menu, move down to passwor service
- 3. Press the yellow "i" button and enter "1432" (Start with the last digit)
- 4. Warning: Do not press F3, since it will erase all pen types in the memory.
- 5. Press F1 Init Counters until the number 1 appears in the field to the right.
- 6. Press F4 Exit.
- 7. Press F2 Manual
- 8. Lift the boom to horizontal level (arrow down).
- 9. Extract the telescope about 0,5m (F1 + arrow up).
- 10. Run the arm out to vertical level (F1 + arrow right).
- 11. Turn the nozzle and stop when it points to the left (F2 + arrow left).
- 12. Park the arm, F1 + arrow left until it stops.
- 13. Park the telescope, F1 + arrow down until it stops.
- 14. Turn the tower approx. 45° to the right of center (arrow right).
- 15. Park the tower, arrow left until it stops.
- 16. Park the boom, arrow up until it stops.
- 17. Press F4 Finish.
- 18. Press F1 Teach.
- 19. Press F2 Arrow keys
- 20. Lift the boom to horizontal level (arrow down).
- 21. Turn the tower approx. 90° to the left (arrow left).
- 22. Turn the tower approx. 90° to the right of the robot (arrow right).
- 23. Park the tower, arrow left until it stops automatically in the center.
- 24. Repeat step 21 to 23.
- 25. Park the boom, arrow up until it stops.
- 26. Press F4 -F4- F2-Finish without saving the pen type.

