

# Arm

Motor: 70 rpm

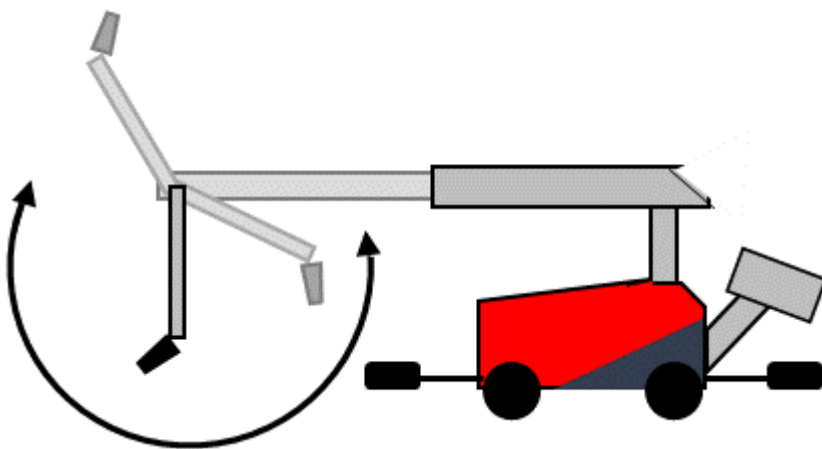
Stroke: parking position to parking+1150, about 315°

Parking: about -55, parallel to boom (more info [about parking here](#))

Zero position sensor: about 15° out from parked position

The arm is one of the circular movements of the robot and should be used predominantly together with the tower and the nozzle during washing.

[See the exploded view of the arm here](#)



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