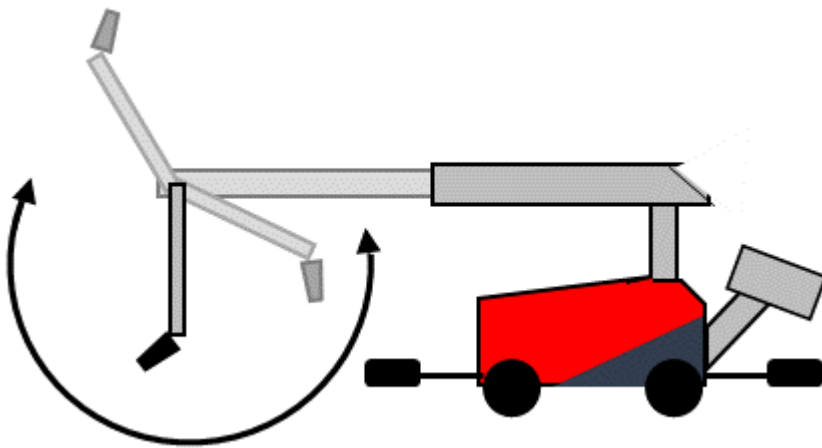# Arm

Motor: 70 rpm

Stroke: parking position to parking+1150, about 315°

Parking: about -55, parallel to boom

The arm is one of the circular movements of the robot and should be used predominantly together with the tower and the nozzle