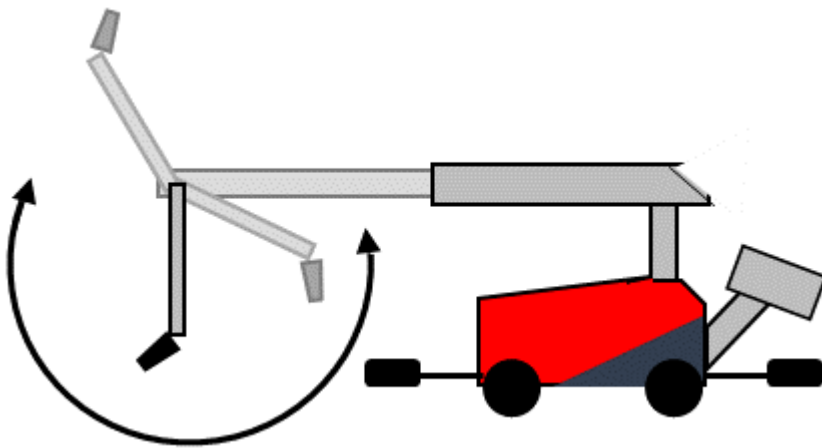# Arm

Motor: 70 rpm

Stroke: parking position to parking+1150, about 315°

Parking: about -55, parallel to boom

Zero position sensor: about 15° out from parked position

The arm is one of the circular movements of the robot and should be used predominantly together with the tower and the nozzle during washing.

See the exploded view of the arm here