Nozzle motor

Motor: 70 rpm with D-profile

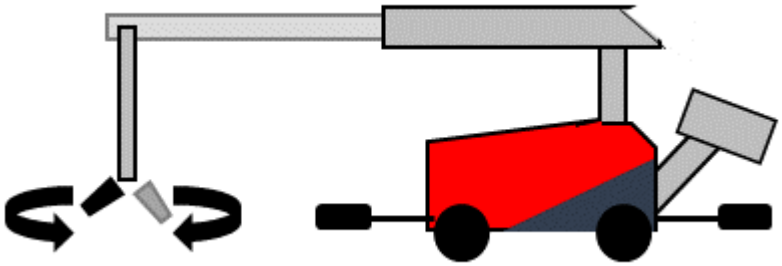
Stroke: unlimited 360° in both directions

Parking: about 0, pointing down when arm is parked (however dependent on the angle the nozzle has been fastened with at the end of the arm)

Zero position sensor: internal

The nozzle is one of the circular movements of the robot and should be used predominantly together with the tower and the arm during washing.

The robot can have two different types of nozzle.
How to use the double nozzle.



See the exploded view of the nozzle motor and gear here

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