Nozzle motor

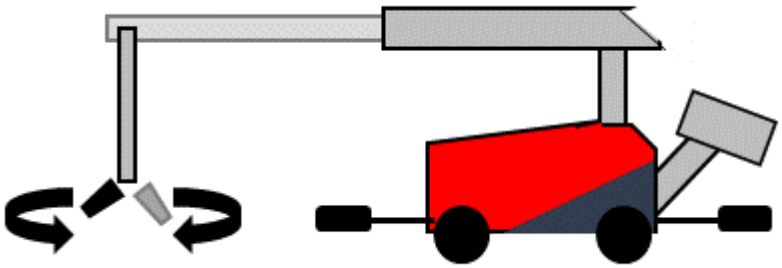
Motor: 70 rpm with D-profile

Stroke: unlimited 360° in both directions

Parking: about 0, pointing down when arm is parked (however dependent on the angle the nozzle has been fastened with at the end of the arm)

Zero position sensor: internal

The nozzle is one of the circular movements of the robot and should be used predominantly together with the tower and the arm during washing.



See the exploded view of the arm here

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