

# Nozzle motor

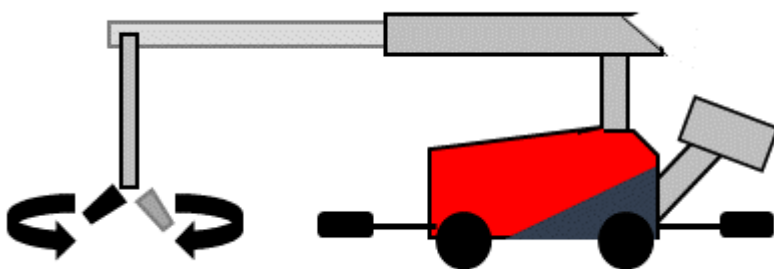
Motor: 70 rpm with D-profile

Stroke: unlimited 360° in both directions

Parking: about 0, pointing down when arm is parked (however dependent on the angle the nozzle has been fastened with at the end of the arm)

Zero position sensor: internal

The nozzle is one of the circular movements of the robot and should be used predominantly together with the tower and the arm during washing.



[See the exploded view of the arm here](#)

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