

# Tower

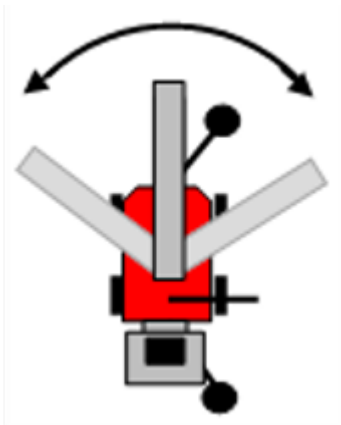
Motor: 70 rpm

Stroke: 1000 in both directions from parking position, about  $\pm 200^\circ$

Parking: about 0, straight forward ([read more here](#))

Zero position sensor: about 0

The tower is one of the circular movements of the robot and should be used predominantly together with the arm and the nozzle during washing.



[See the exploded view of the gearbox here](#)

[and exploded view of tower assembly here](#)

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