Tower

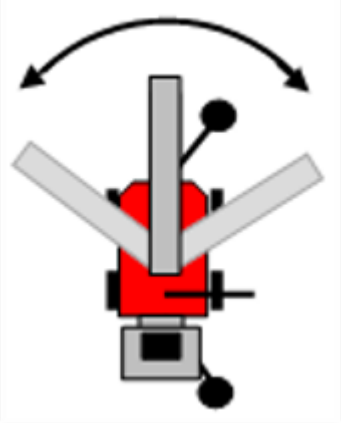
Motor: 70 rpm

Stroke: 1000 in both directions from parking position, about ±200°

Parking: about 0, straight forward (read more here)

Zero position sensor: about 0

The tower is one of the circular movements of the robot and should be used predominantly together with the arm and the nozzle during washing.



See the exploded view of the gearbox here

and exploded view of tower assembly here

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