

Tower

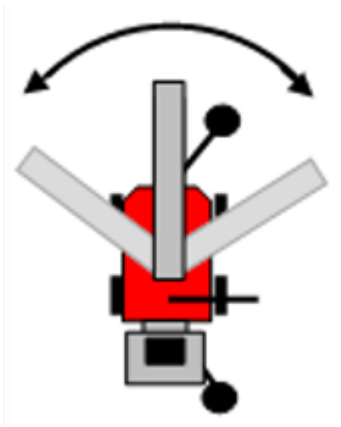
Motor: 70 rpm

Stroke: 1000 in both directions from parking position, about $\pm 200^\circ$

Parking: about 0, straight forward ([read more here](#))

Zero position sensor: about 0

The tower is one of the circular movements of the robot and should be used predominantly together with the arm and the nozzle during washing.



[See the exploded view of the tower and gearbox here](#)

From:
<https://wiki.envirologic.se/> - **Envirologic Support Wiki**

Permanent link:
https://wiki.envirologic.se/doku.php/parts:tower_motor?rev=1600927094

Last update: **2020/09/23 22:58**

