

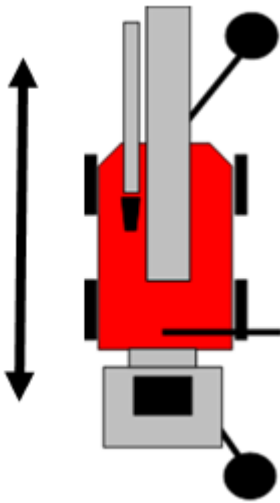
# Wheels motor

Motor: 220 rpm

Stroke: unlimited forward and backward

Zero position sensor: none, robot uses [magnetic marker sensor](#) to zero position errors in the robot's direction

The wheels motor is used to take new positions in the robot's direction in order to continue to wash predominantly with [tower](#), [arm](#) and [nozzle](#).



[See the exploded view of the wheels motor and gearbox here](#)

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