

Troubleshooting - alarms

Which alarm is shown on the screen? If you have already left the alarm screen you can go to Settings>Alarm list>Alarm history.

- First marker not found within 500 pulses
- File operation failed during teach
- Robot stuck too many times
- Unexpected PCB reset
- Water turned off due to stuck motors
- File operation failed during recipe edit
- PCB communication failure
- PCB communication watchdog triggered
- Hose reel stuck
- Water pressure too high
- Water pressure too low
- Ongoing wash aborted unexpectedly
- Homing needed
- Battery voltage low
- Over current detected
- Battery idle voltage low
- SELF_TEST_FAILED
- Marker missed
- Marker magnetic switch failure
- Motor] missing pulses in [a] direction
- Reel missing pulses
- Boom stuck in upward direction
- Boom stuck in downward direction
- Tower stuck in right direction
- Tower stuck in left direction
- Wheels stuck in backward direction
- Wheels stuck in forward direction
- Telescope stuck
- telescope_stuck_in_inward_direction
- Arm stuck in outward direction
- Arm stuck in inward direction
- Nozzle stuck in clockwise direction
- Nozzle stuck in counter-clockwise direction
- Missing zero position sensor for tower
- Missing zero position sensor for telescope
- Missing zero position sensor for arm
- Missing zero position sensor for nozzle
- Boom unexpected large position change detected
- Tower unexpected large position change detected
- Wheels unexpected large position change detected
- Telescope unexpected large position change detected

- Arm unexpected large position change detected
- Nozzle unexpected large position change detected
- Boom no current detected
- Tower no current detected
- Wheels no current detected
- Telescope no current detected
- Arm no current detected
- Nozzle no current detected
- Reel no current detected
- Backup to secondary storage failed
- Remote backup preparation failed
- Remote backup communication error

From:

<https://wiki.envirologic.se/> - **Envirologic Support Wiki**



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